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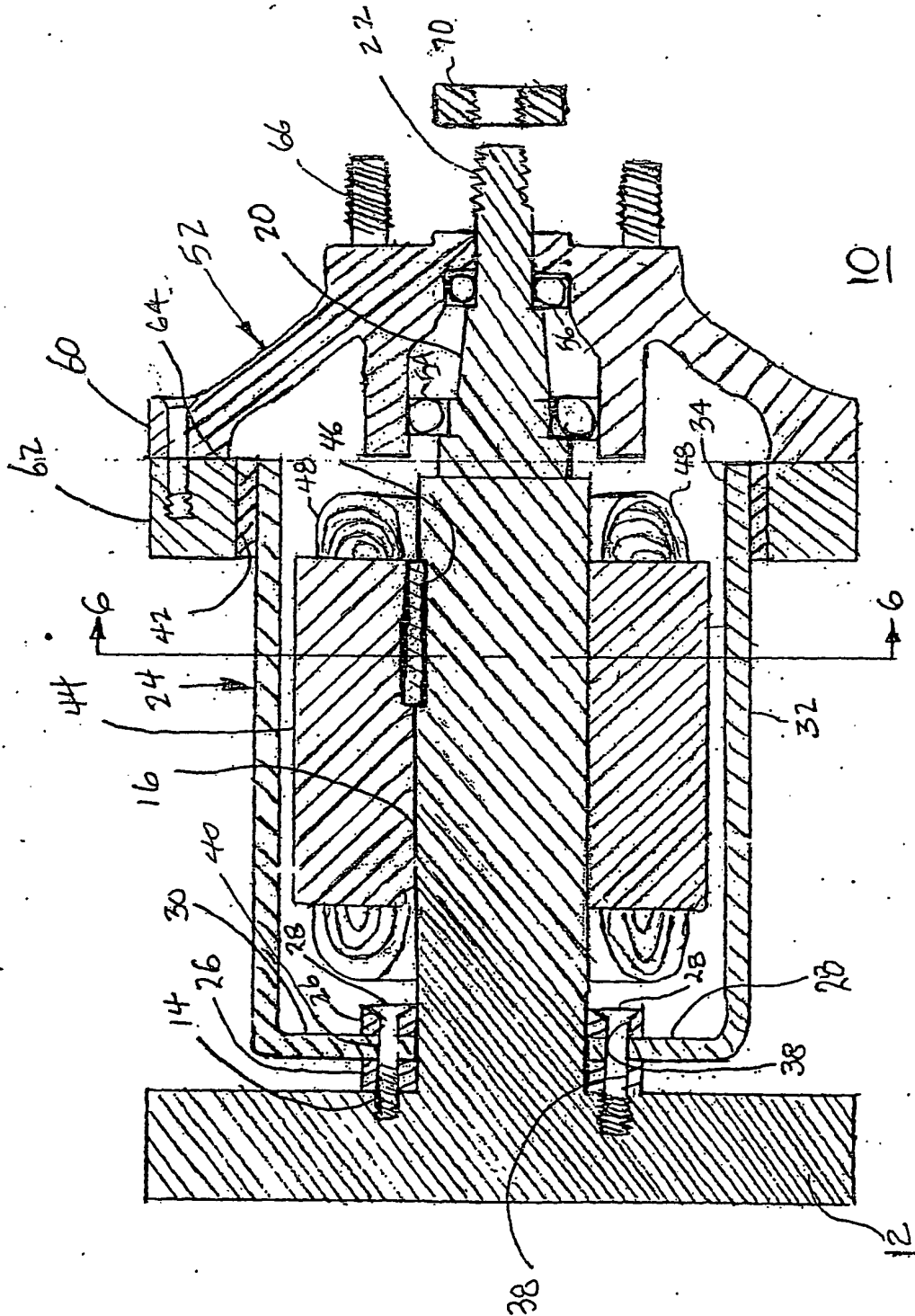


FIGURE 1

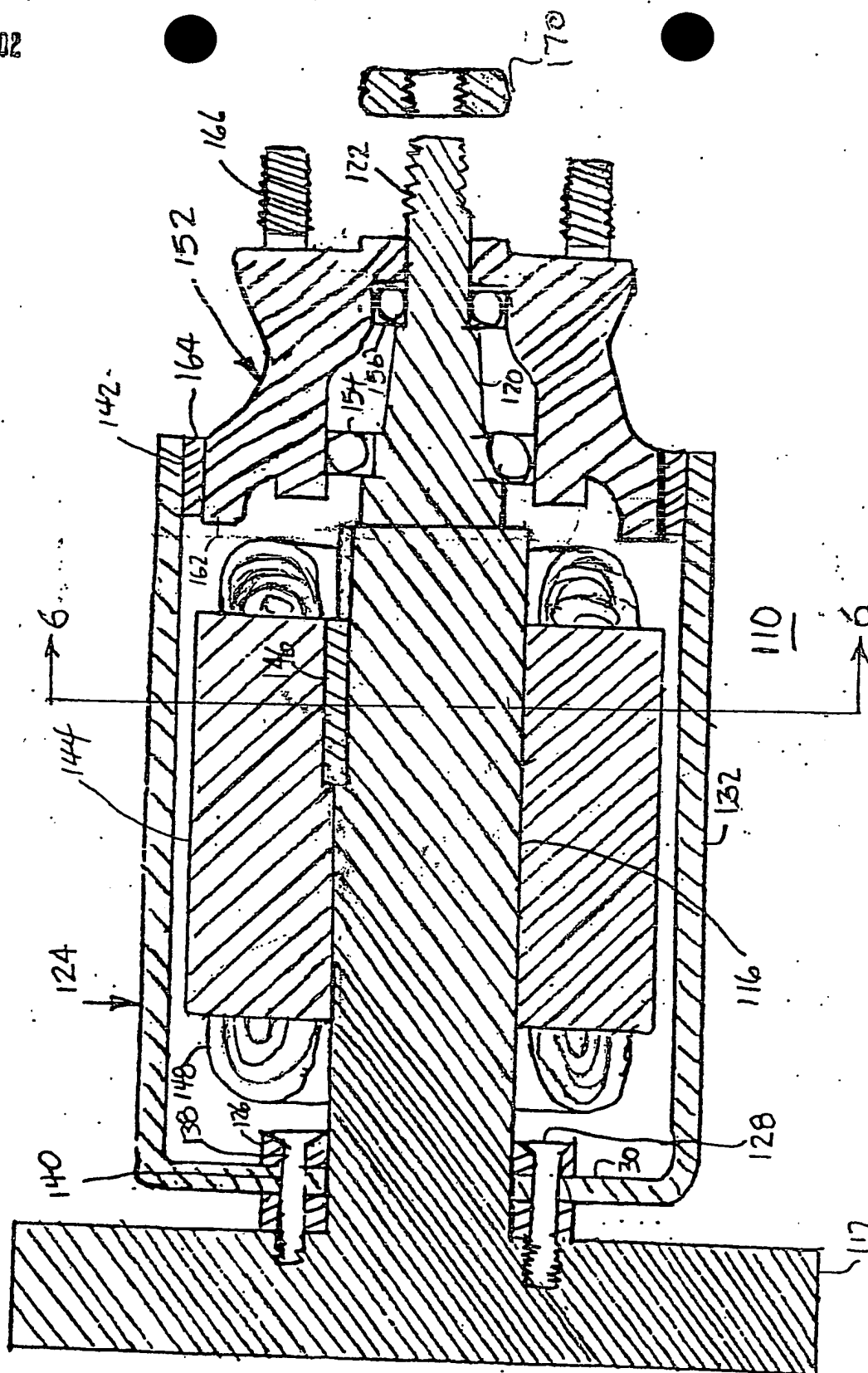


FIGURE 2

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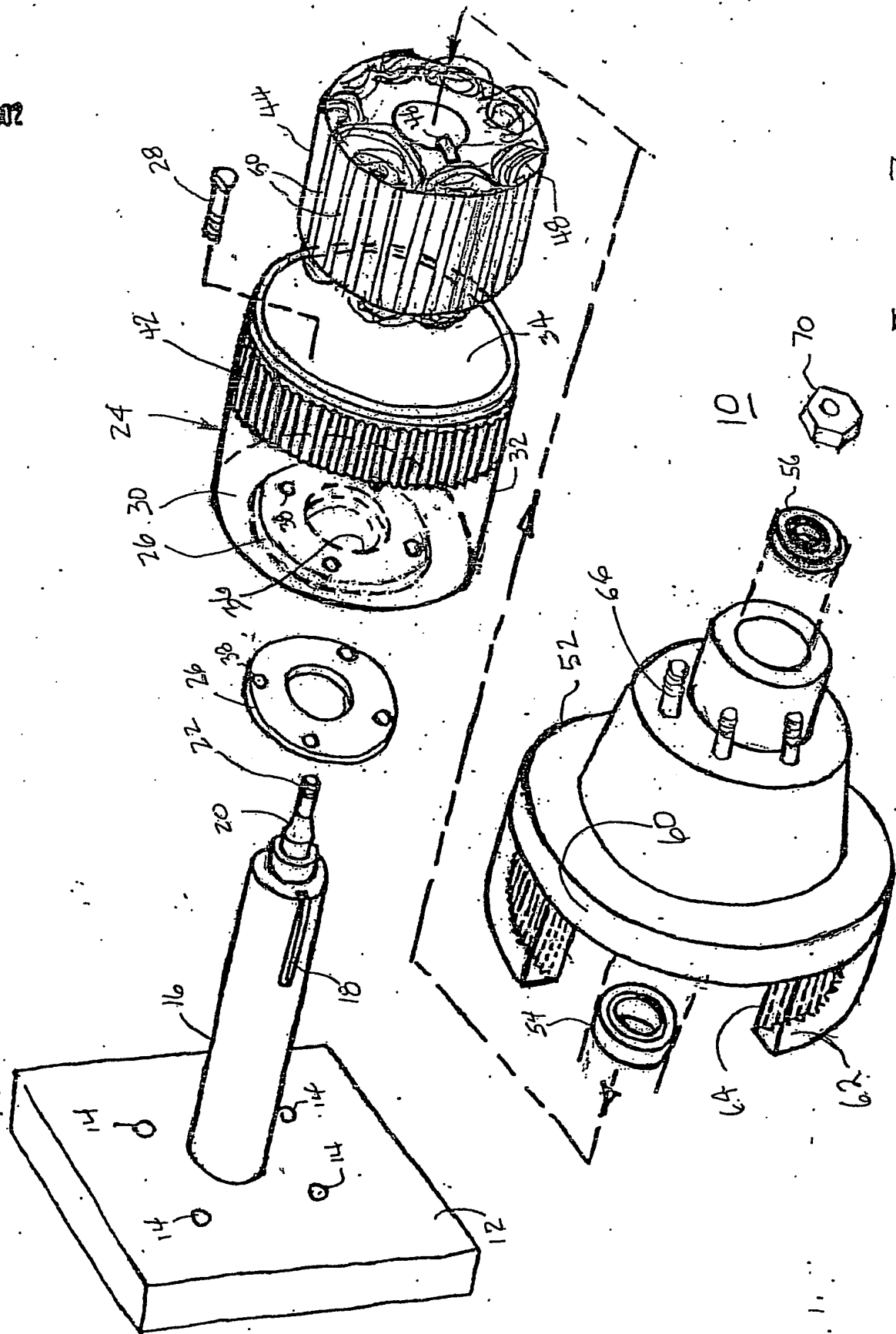


FIGURE 3

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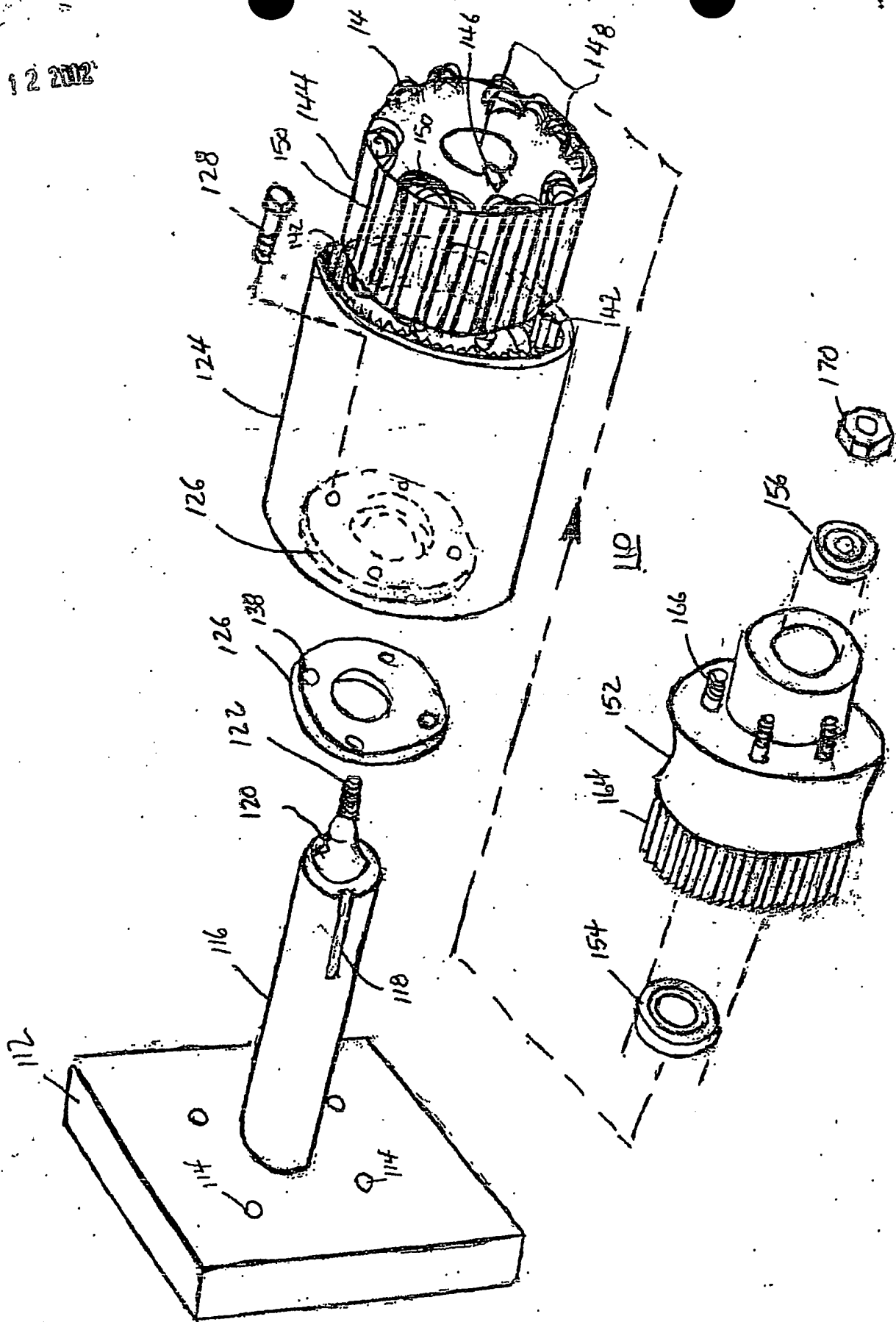


FIGURE 4

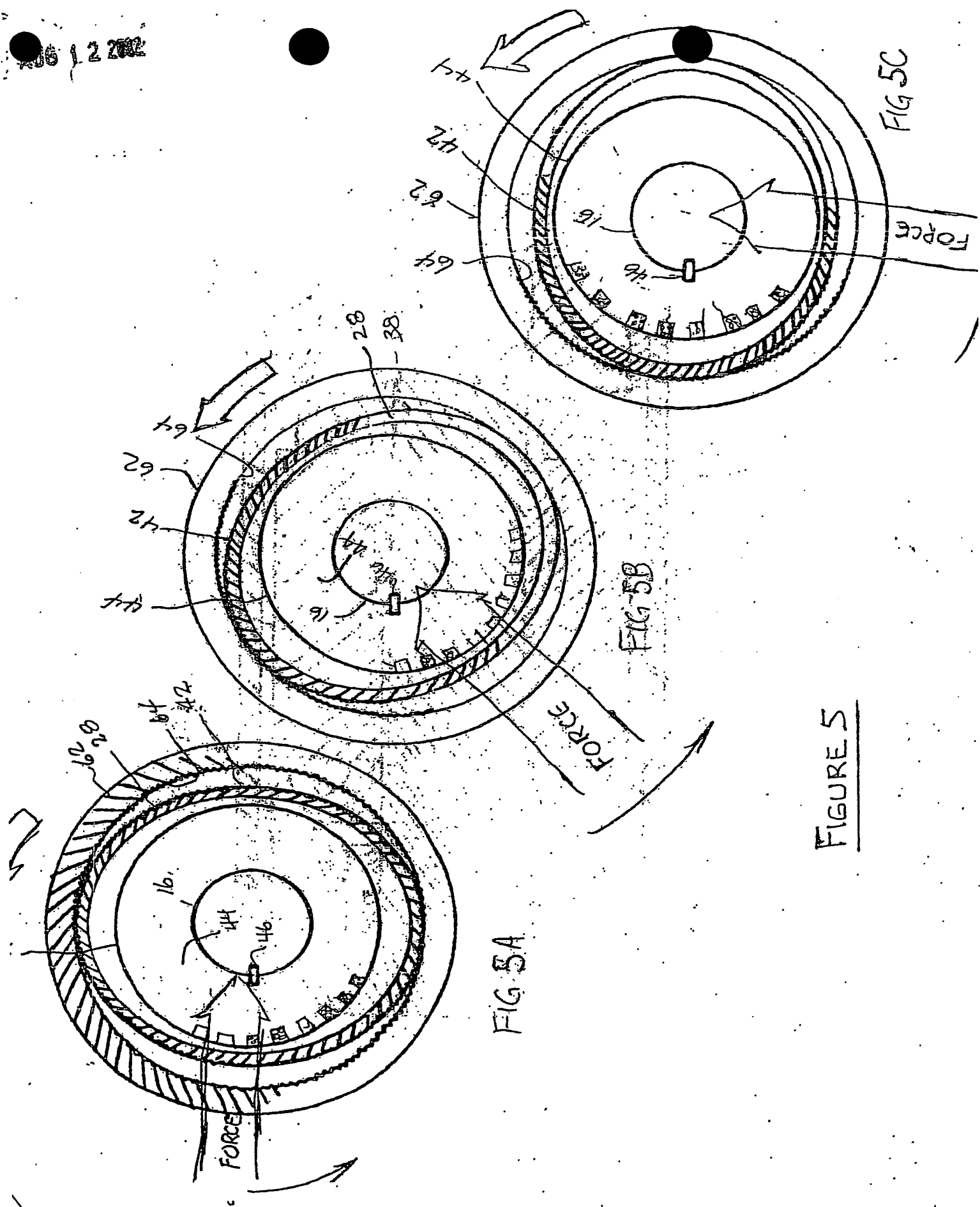


FIGURE 5

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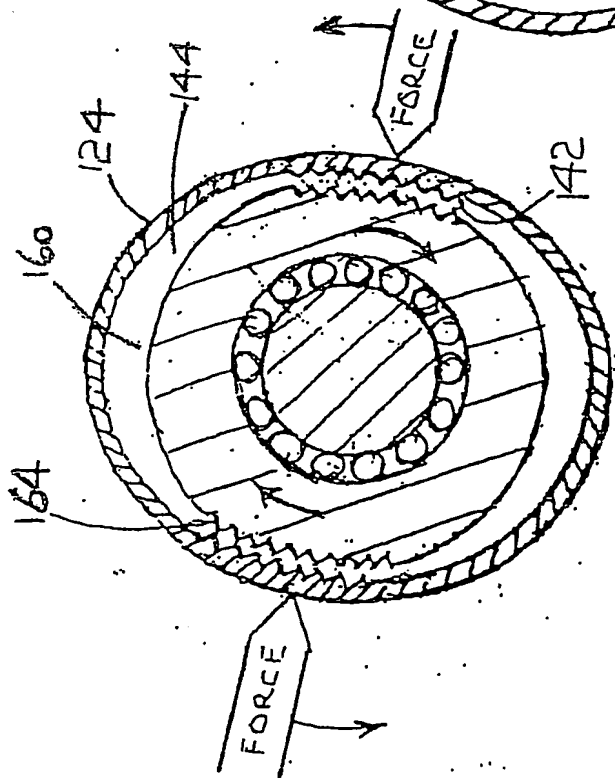


FIG 6A

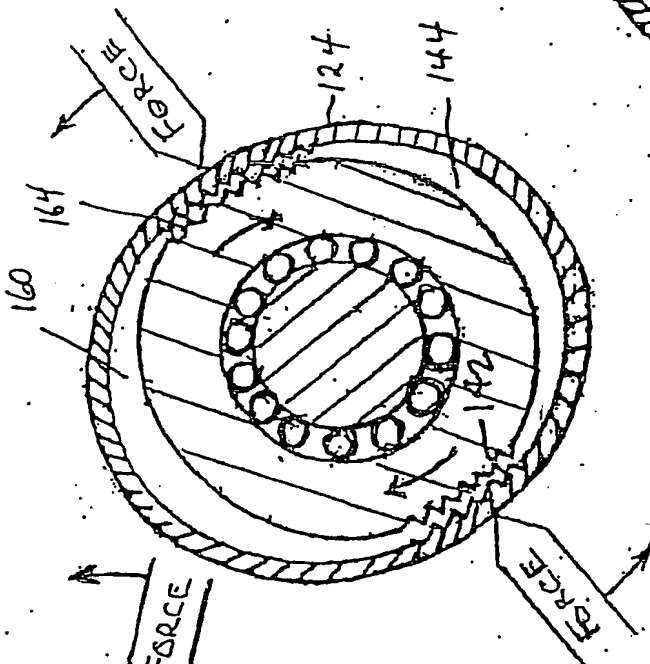


FIG 6B

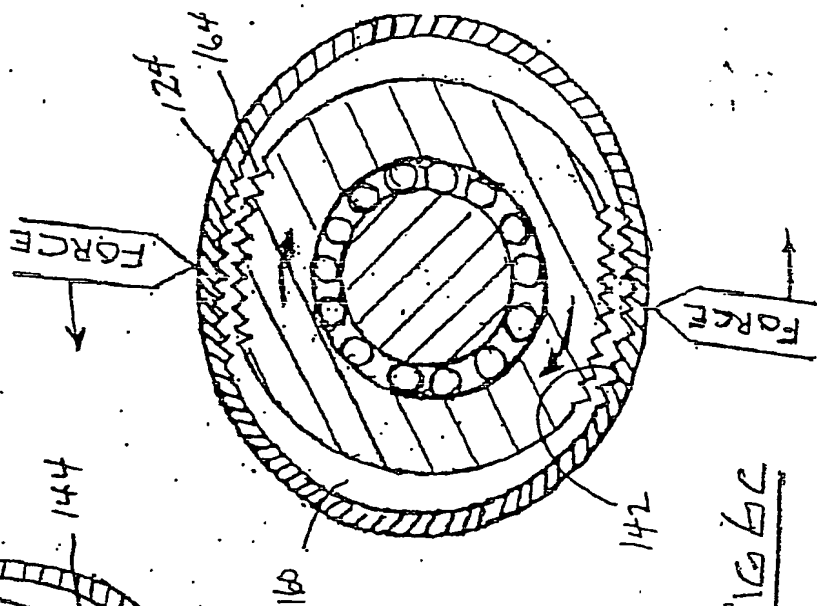


FIG 6C

FIGURE 6

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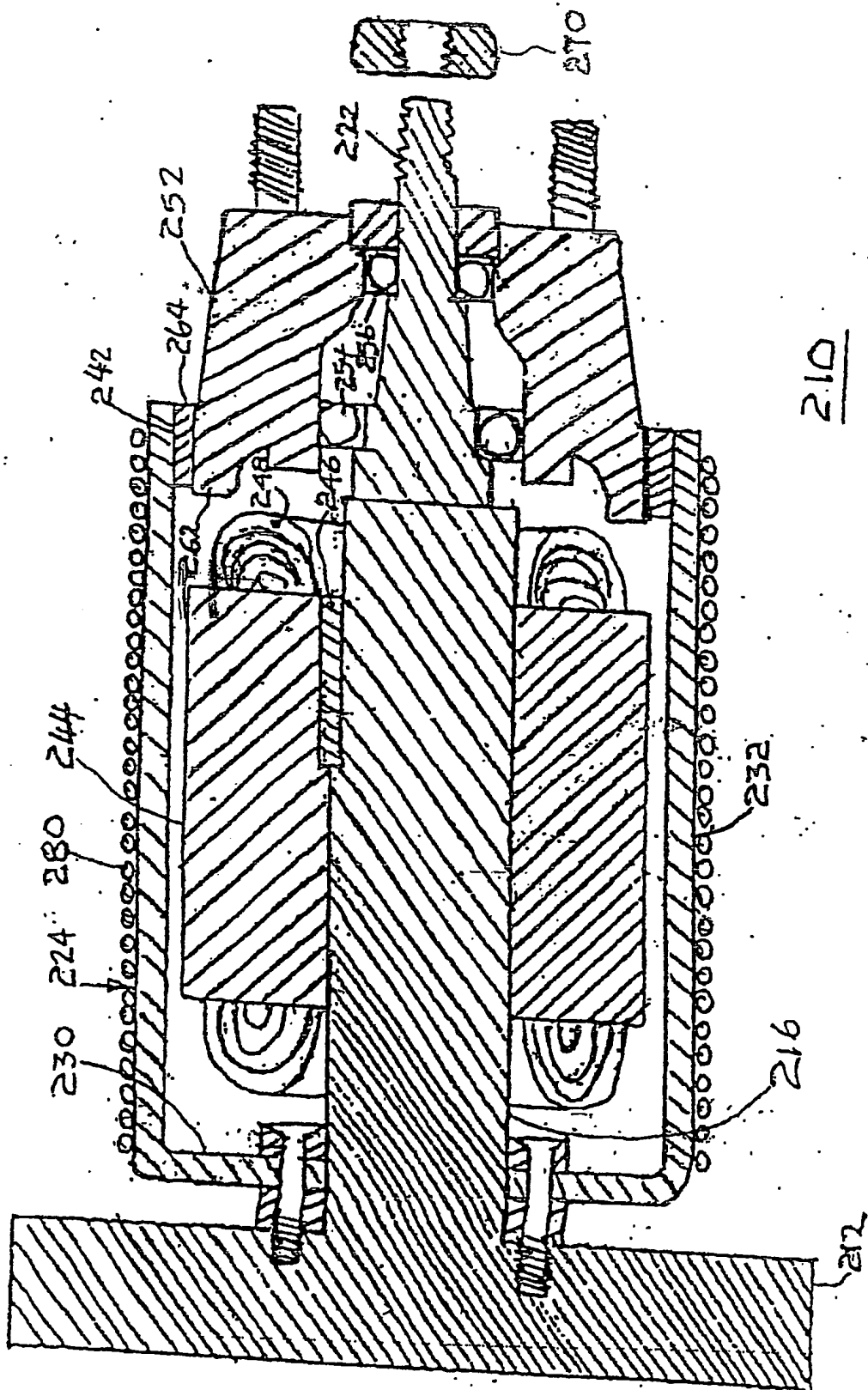


FIGURE 7

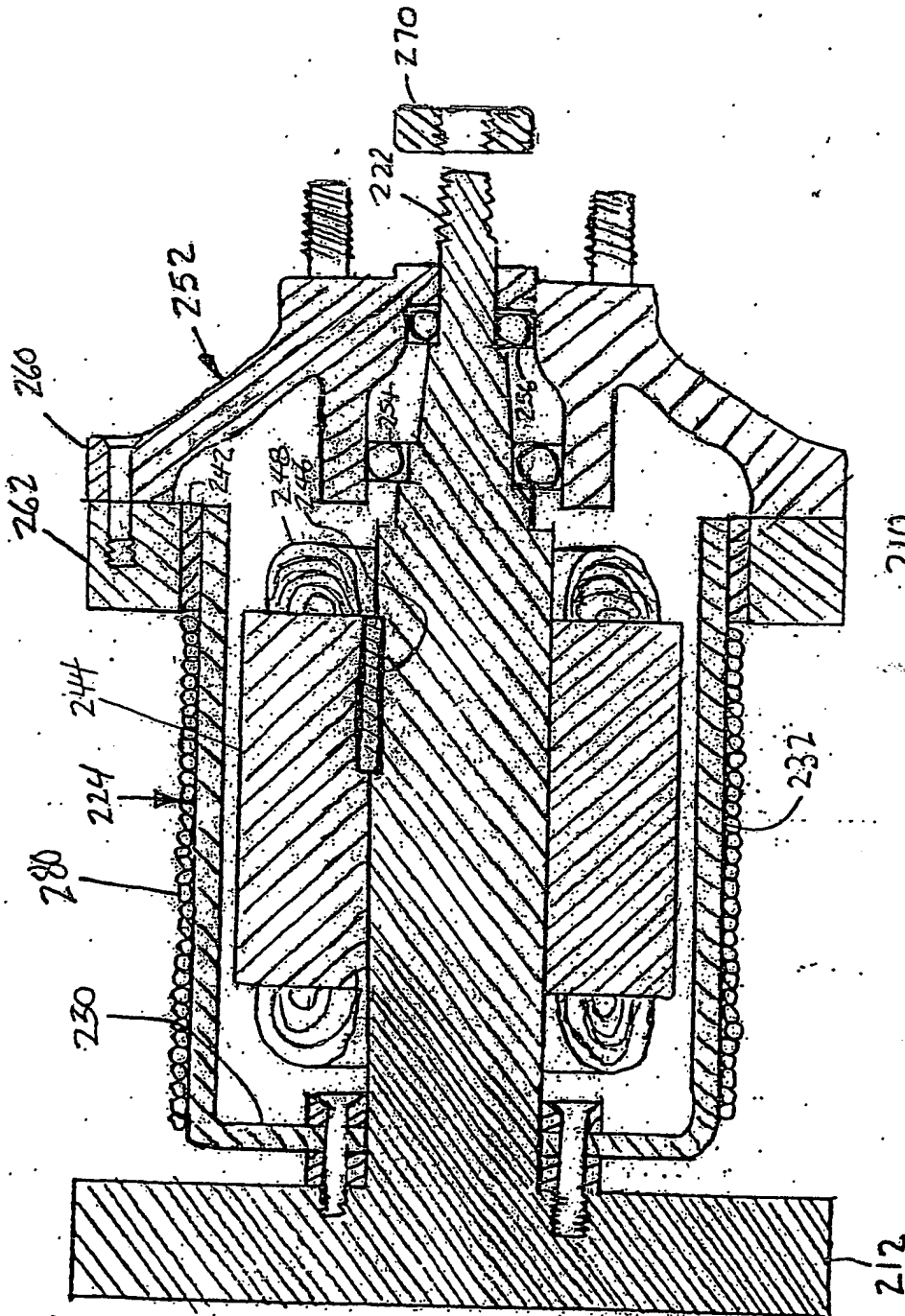


FIGURE 8

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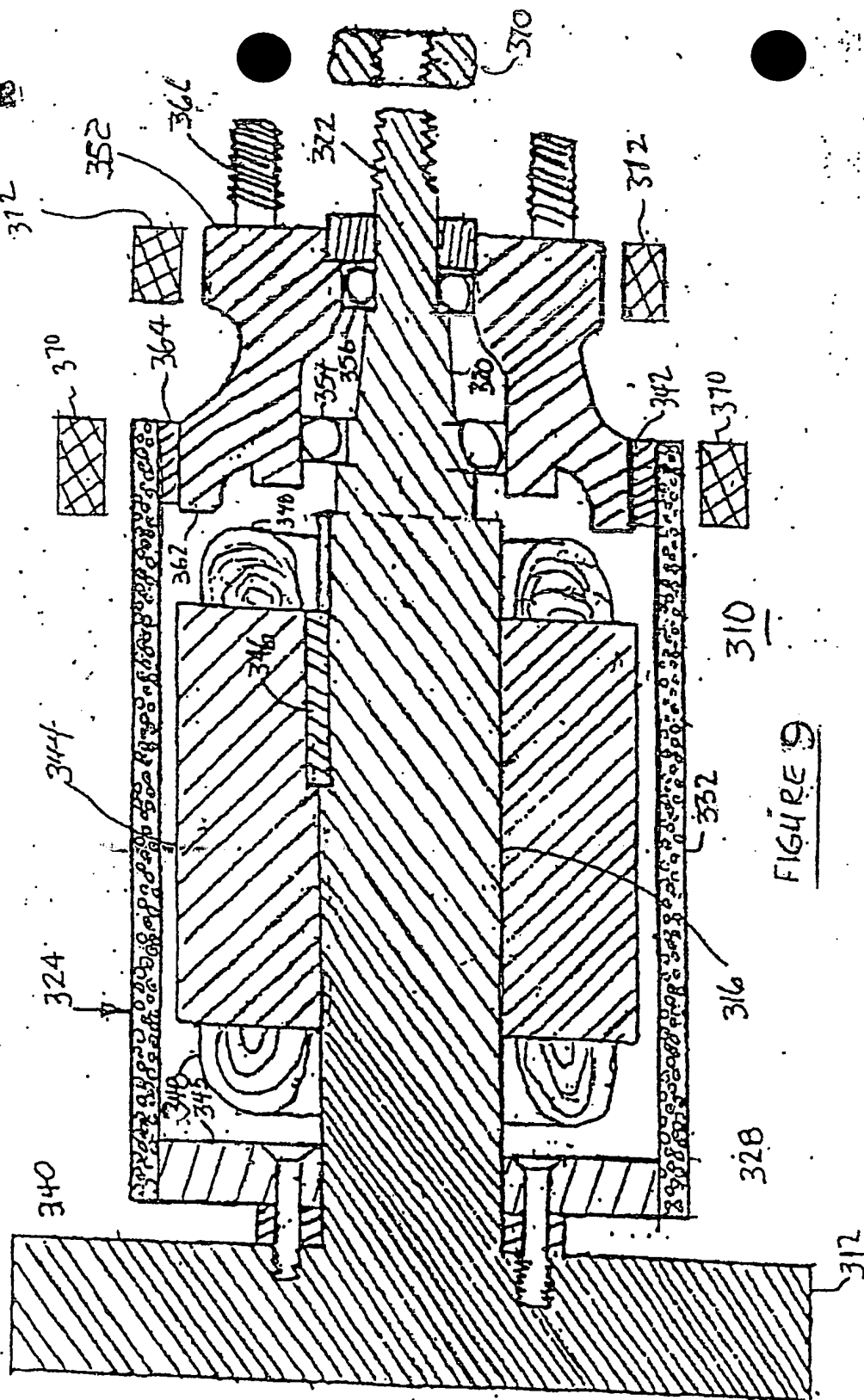
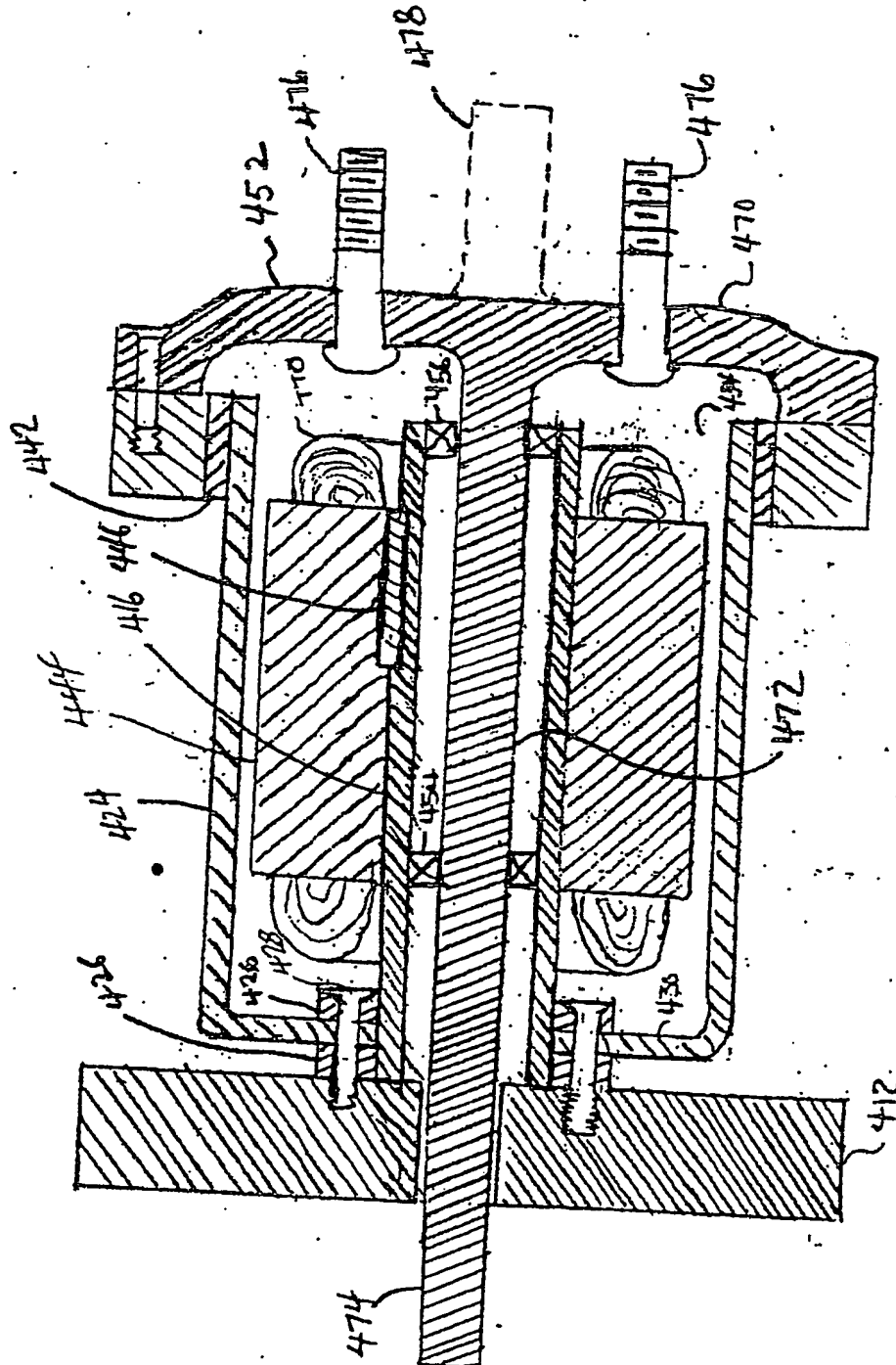


FIGURE 9

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410

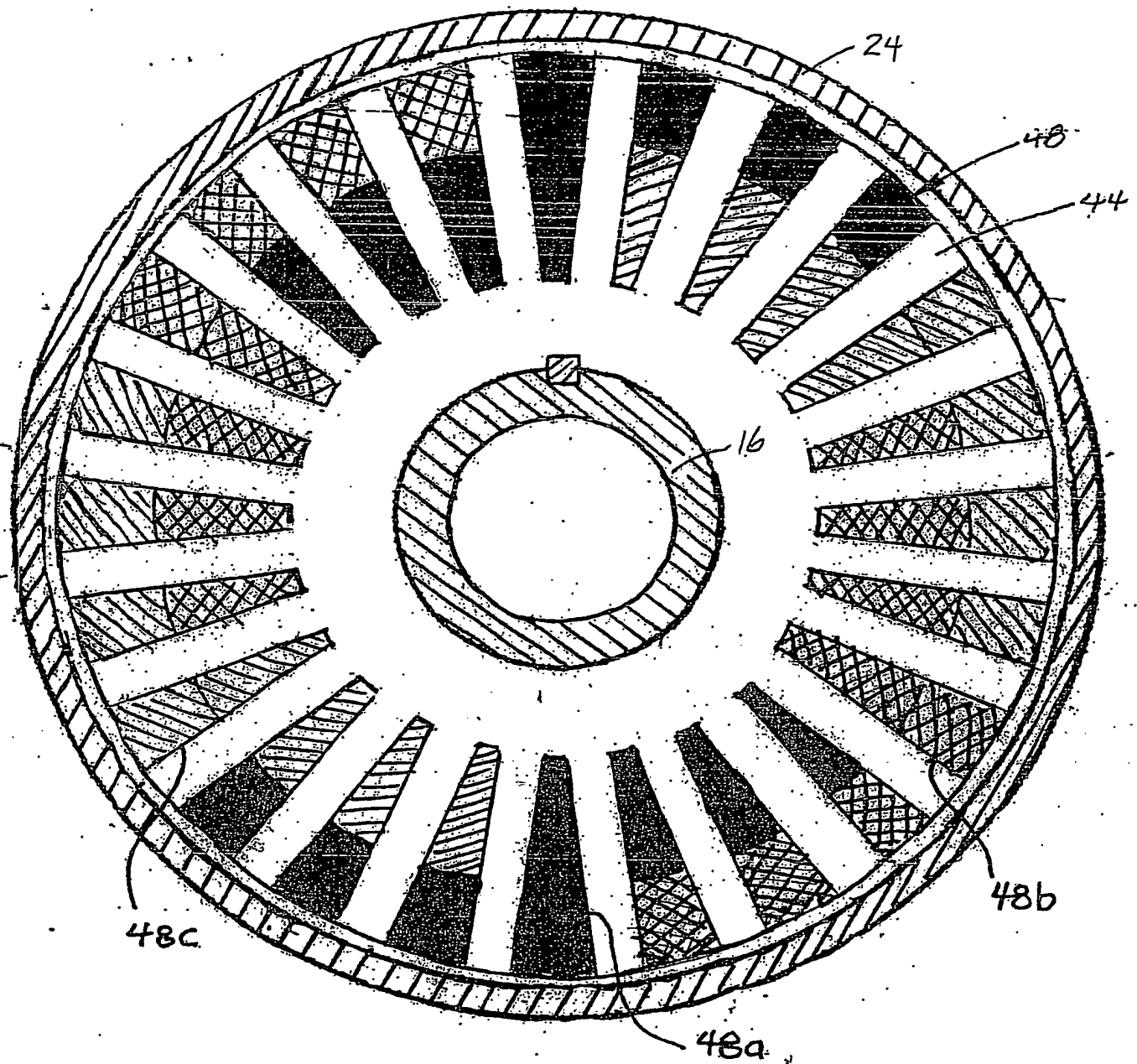


FIGURE 11

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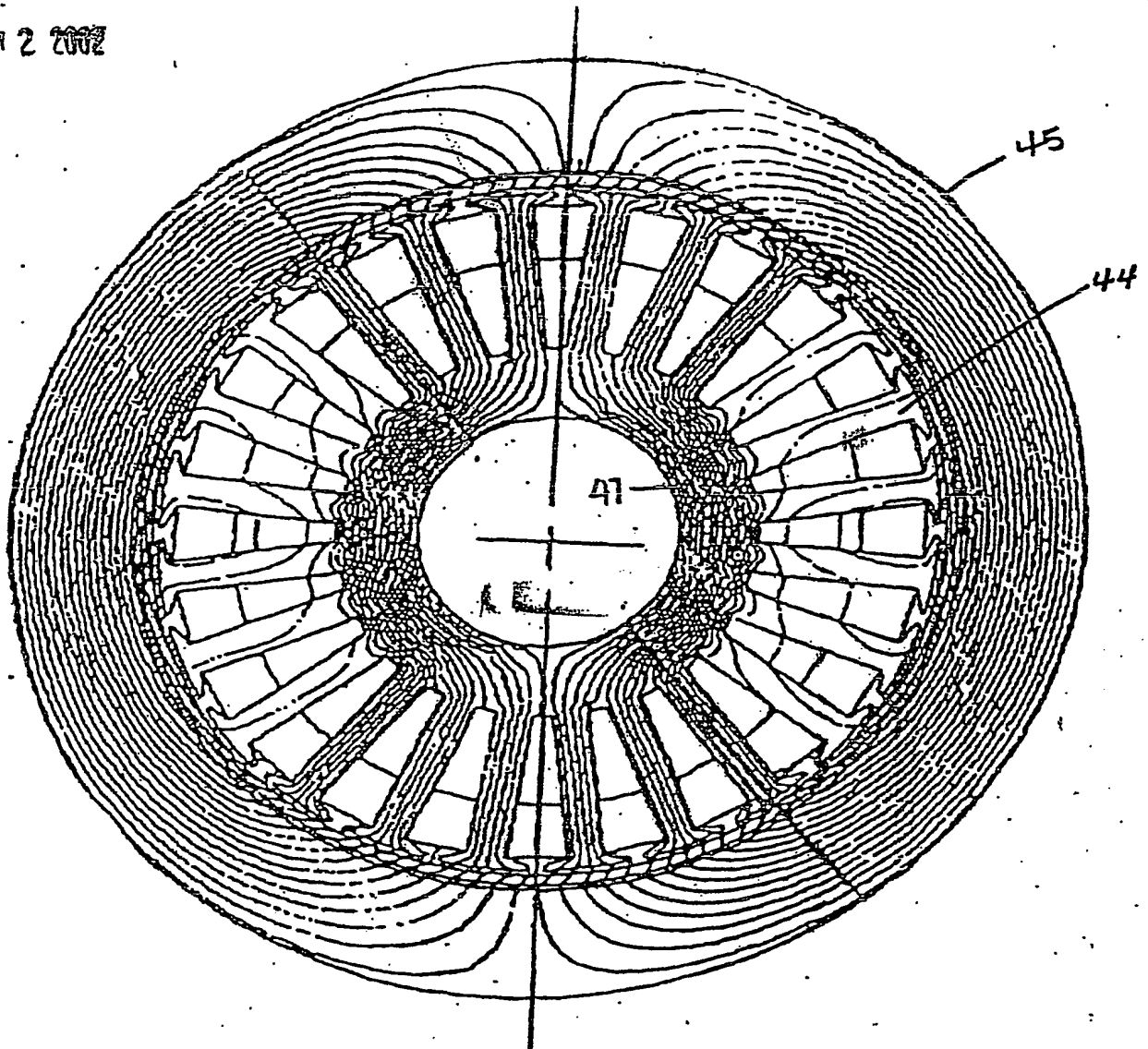


FIGURE 12

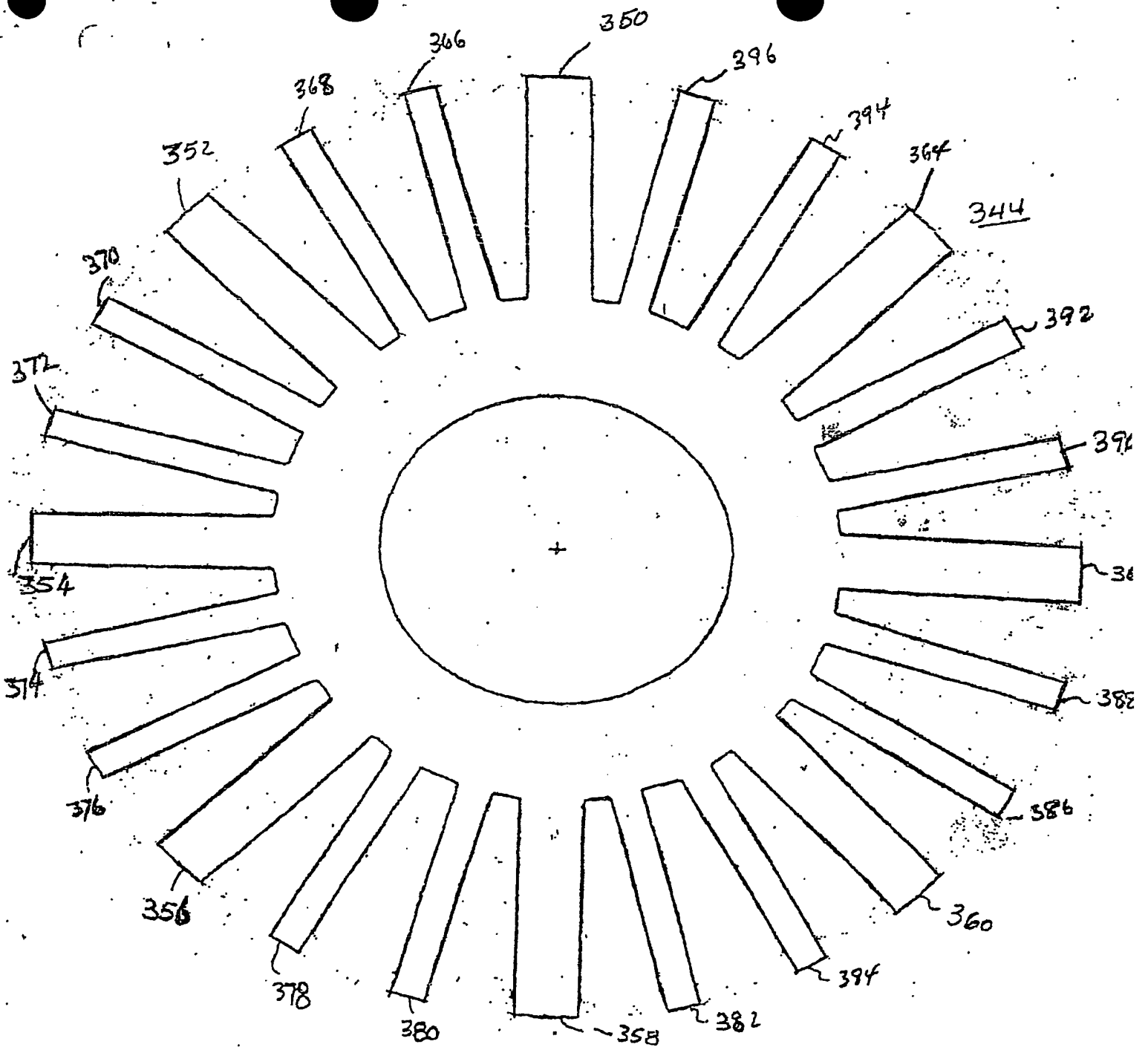


FIGURE 13

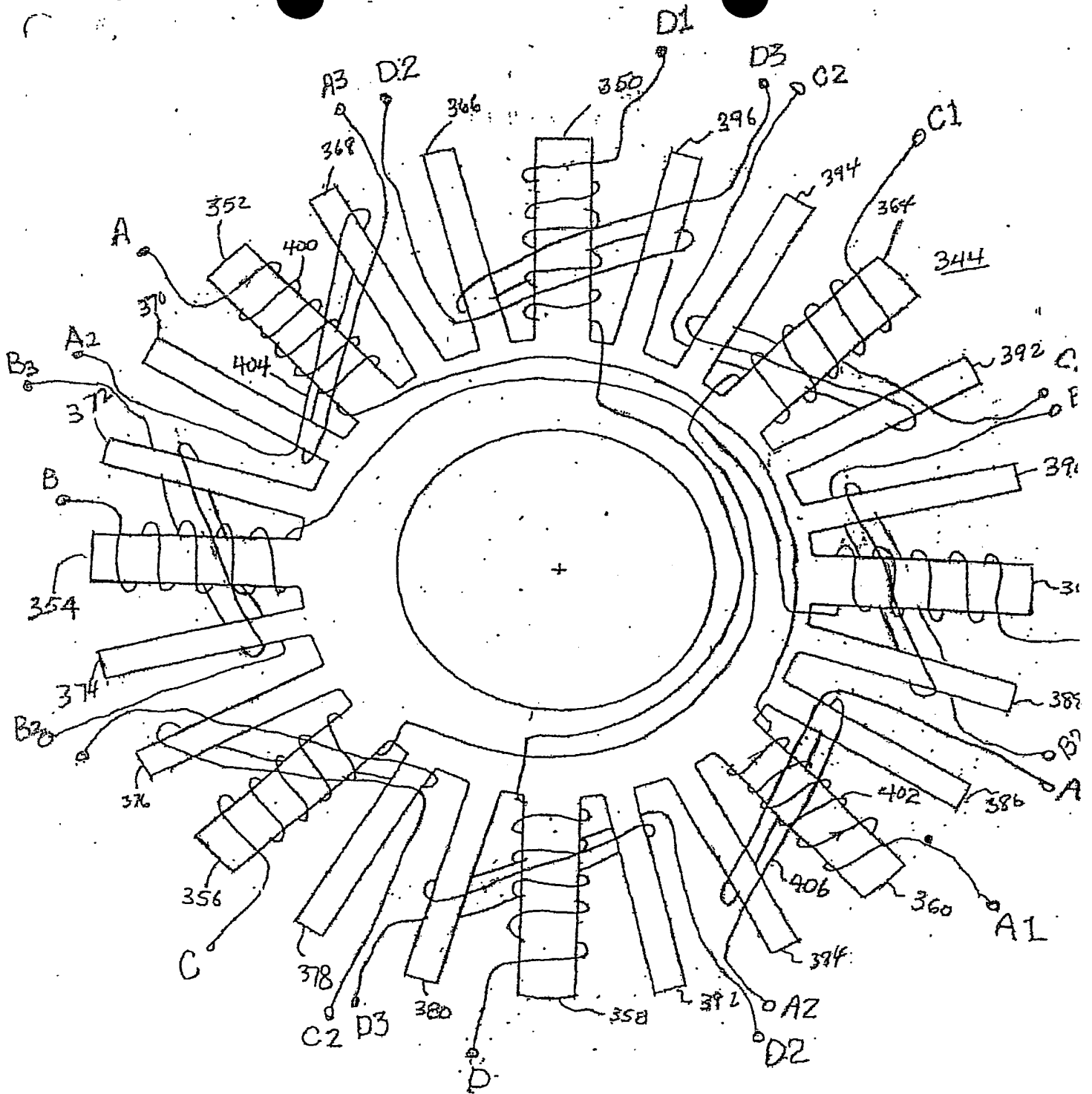
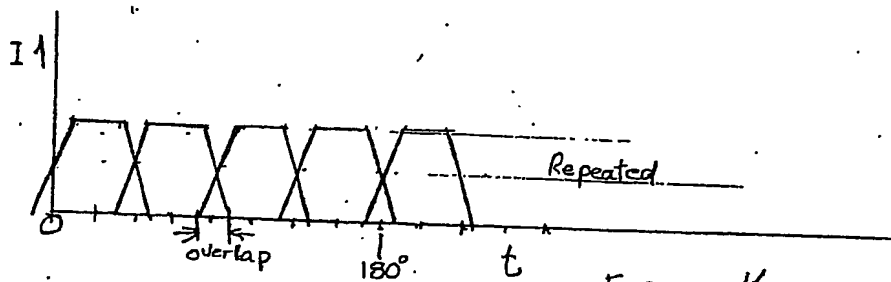
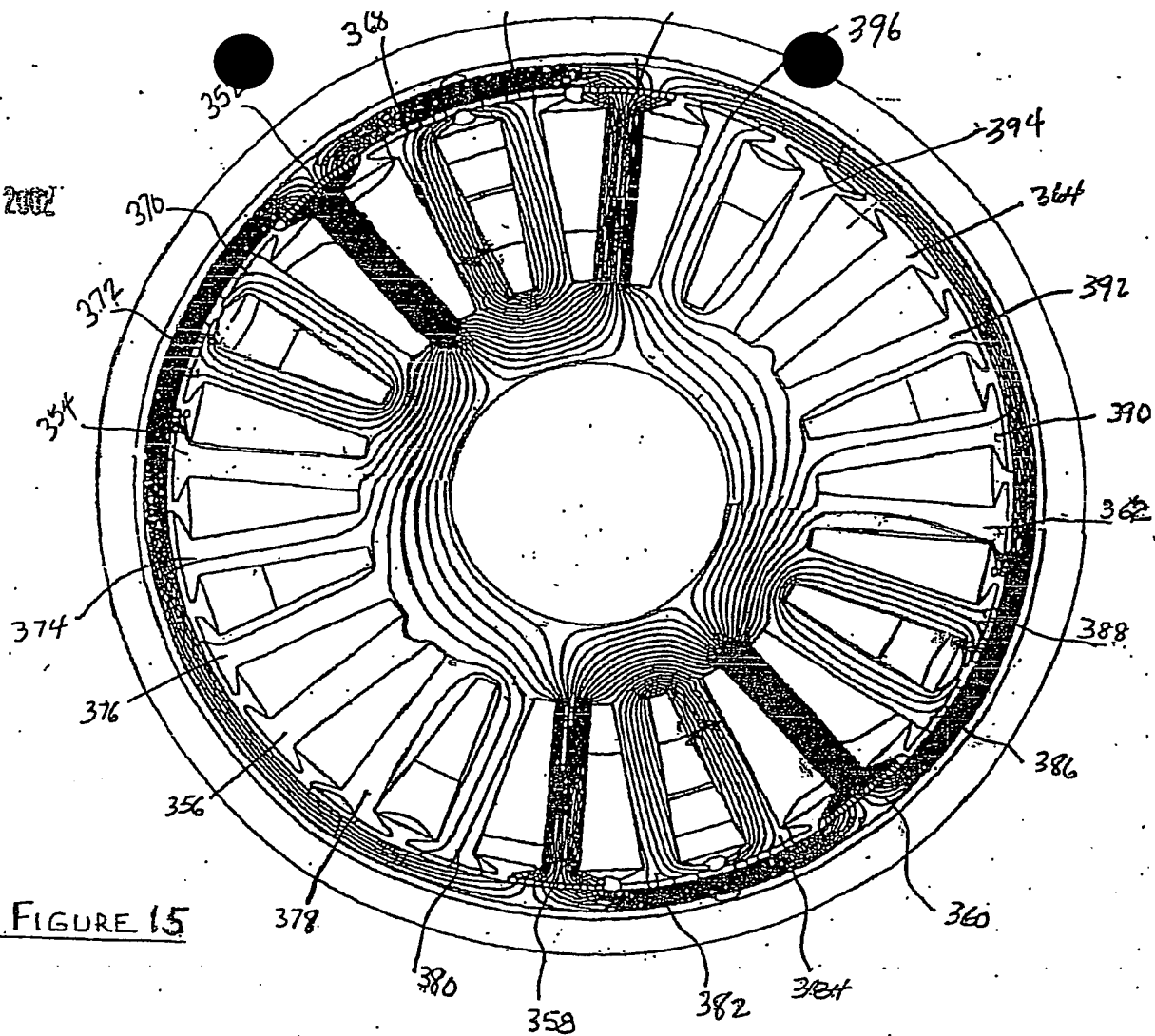


FIGURE 14

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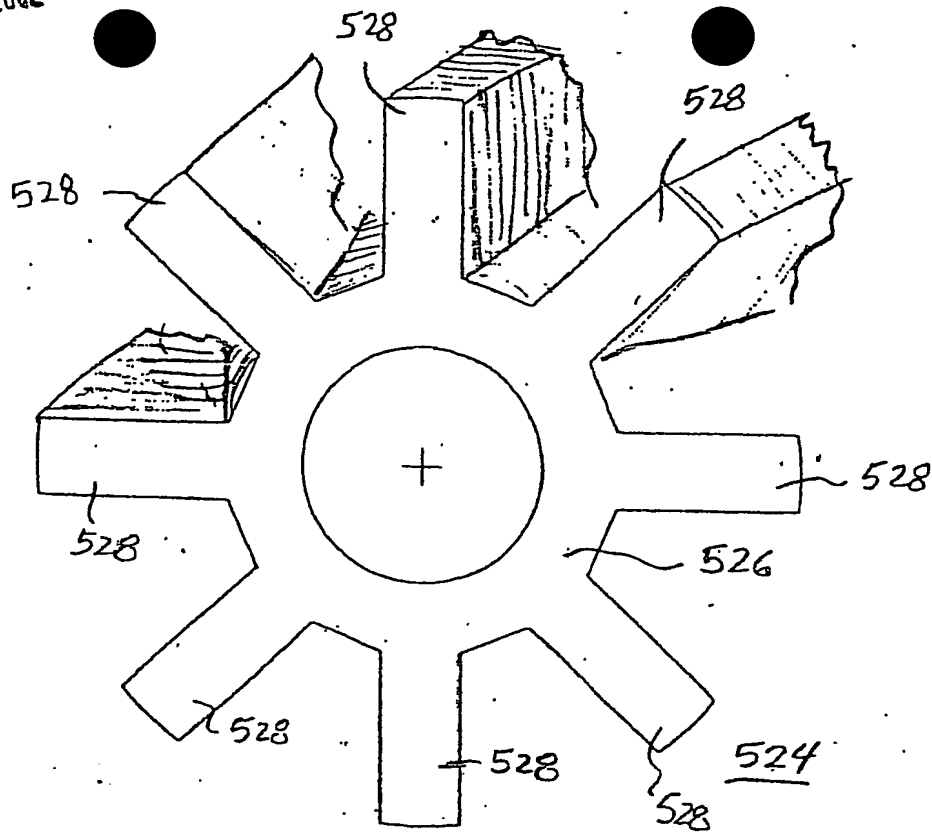


FIGURE 17

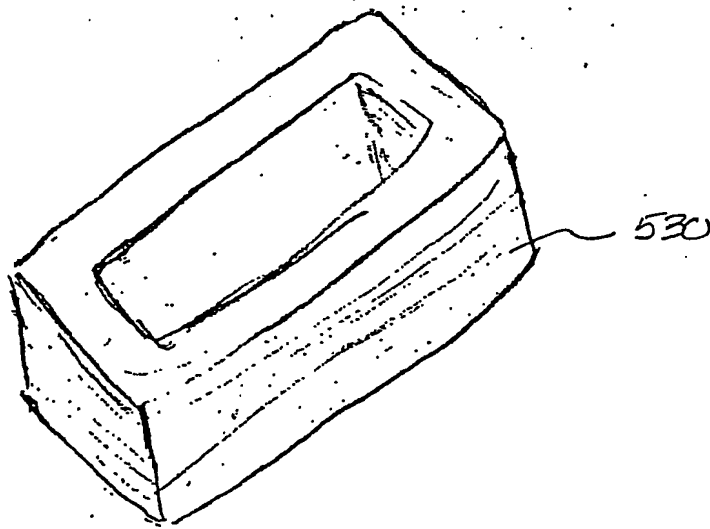
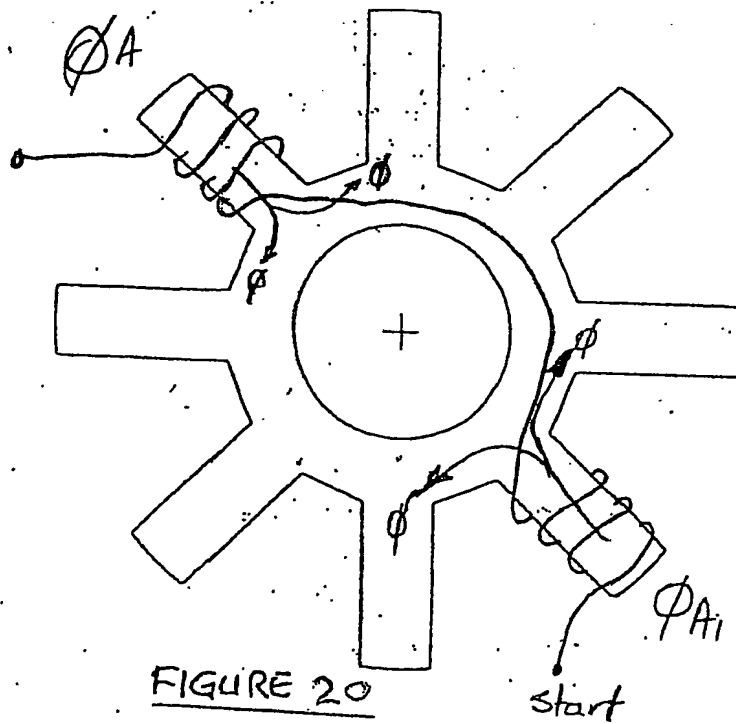
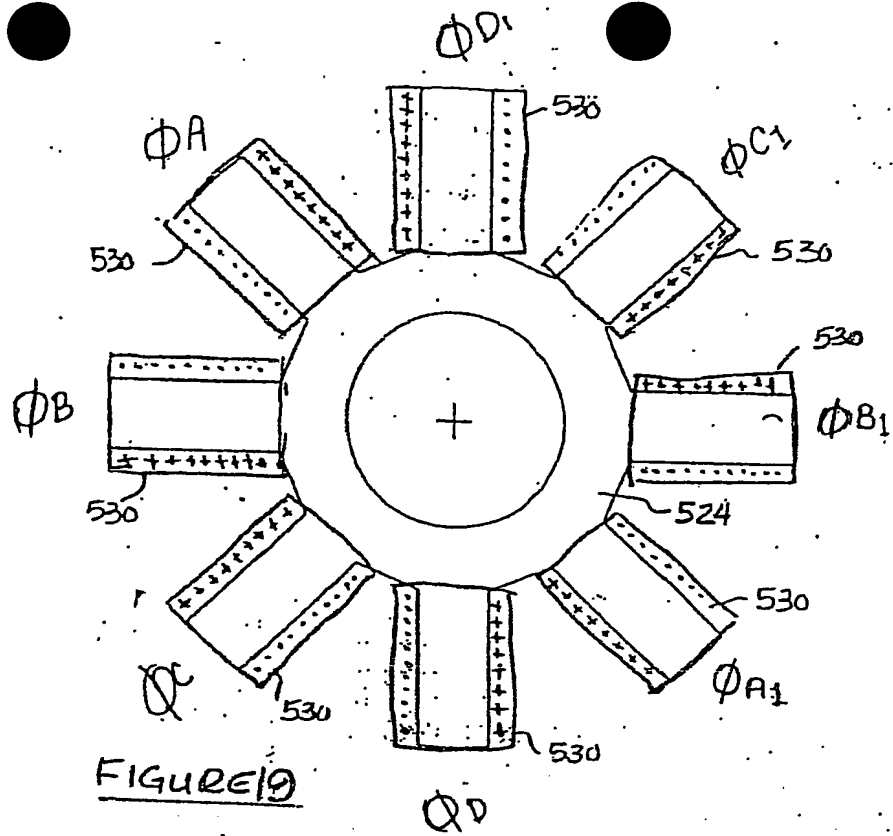


FIGURE 18

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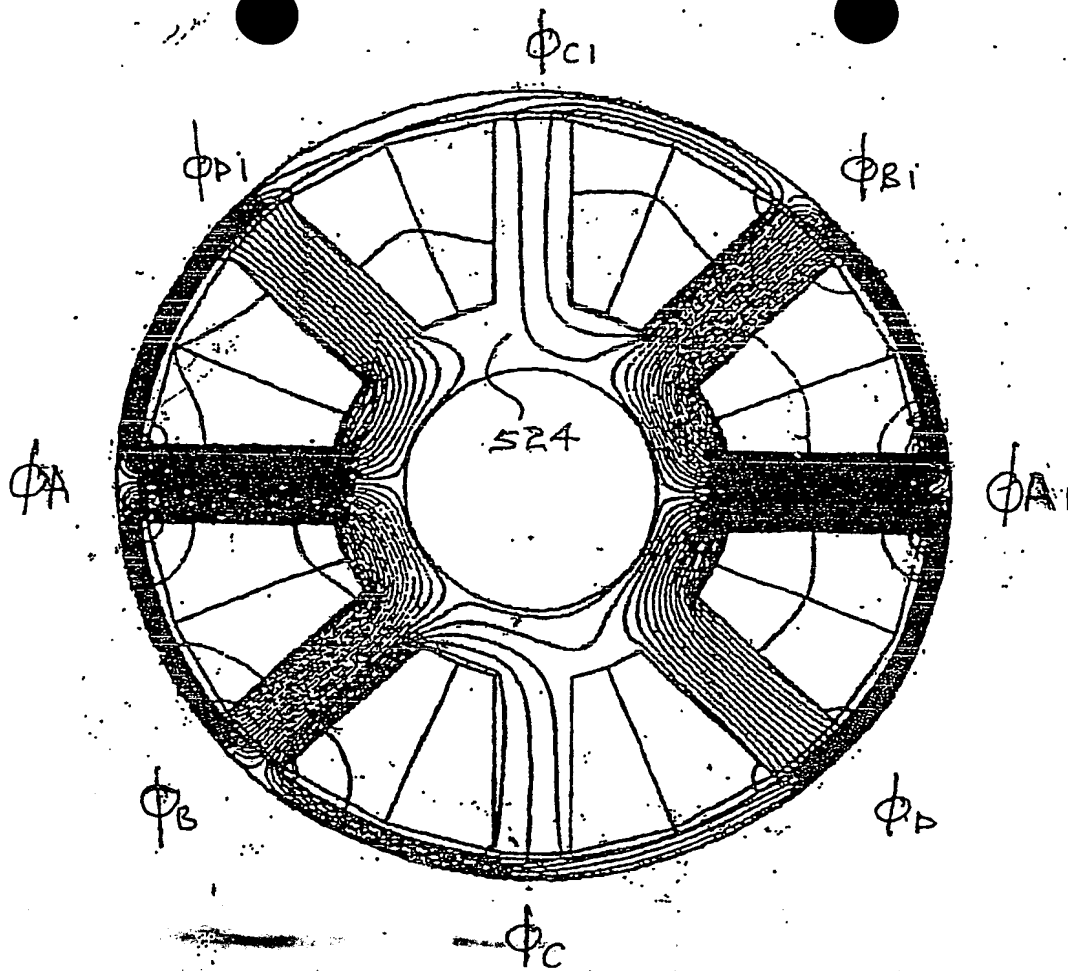


FIGURE 21

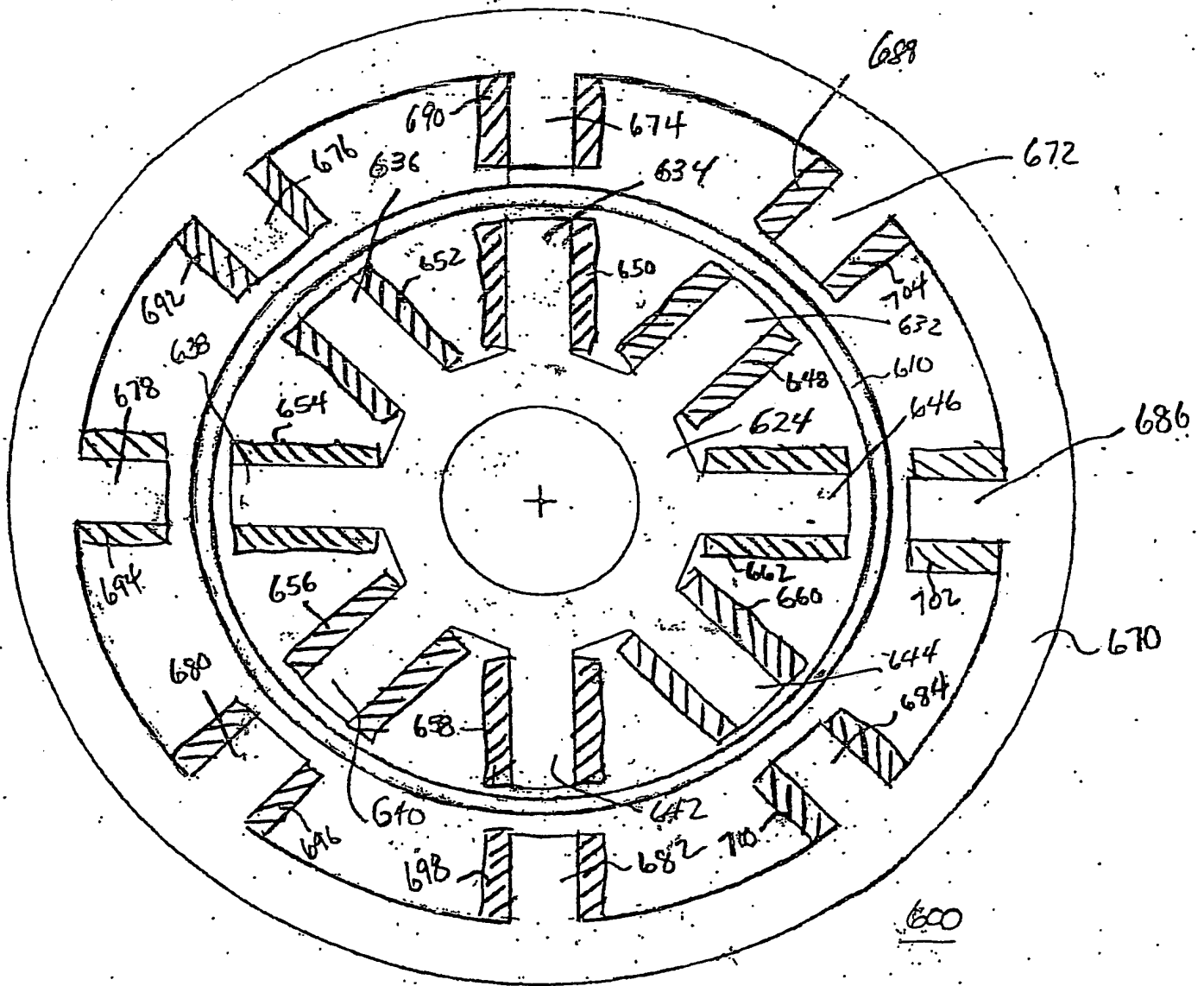


FIGURE 22

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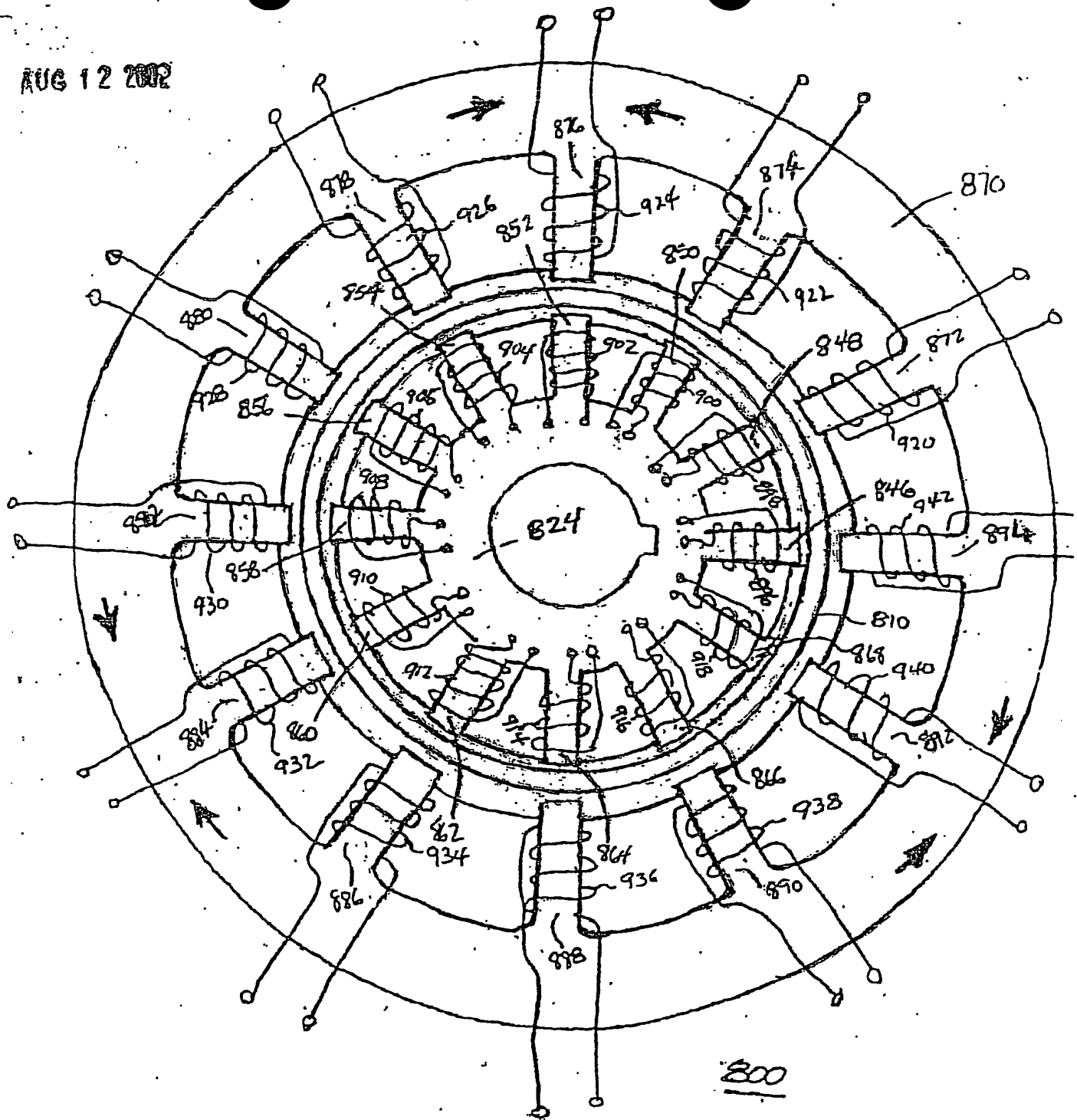
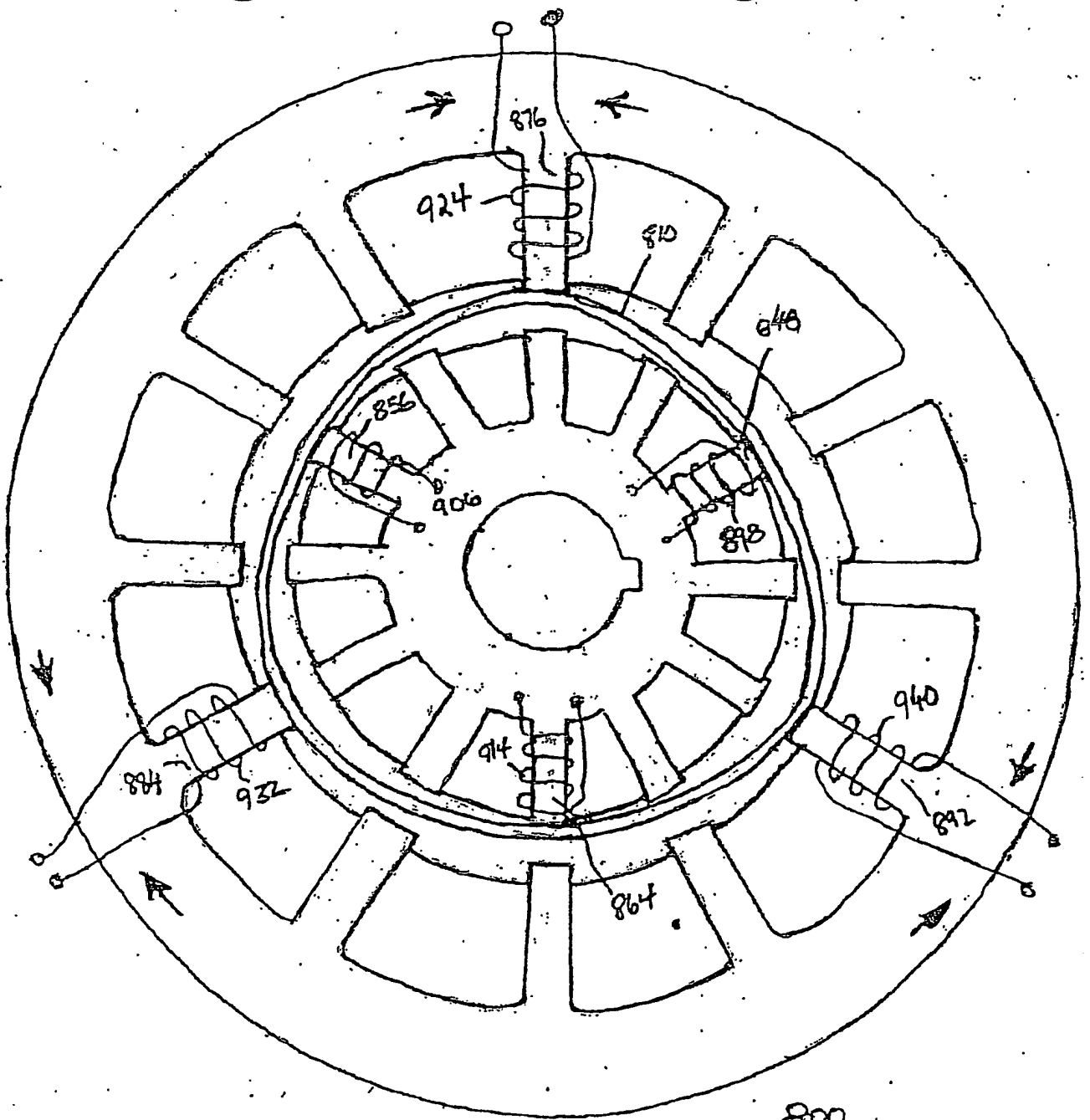


FIGURE 23



800

FIGURE 24

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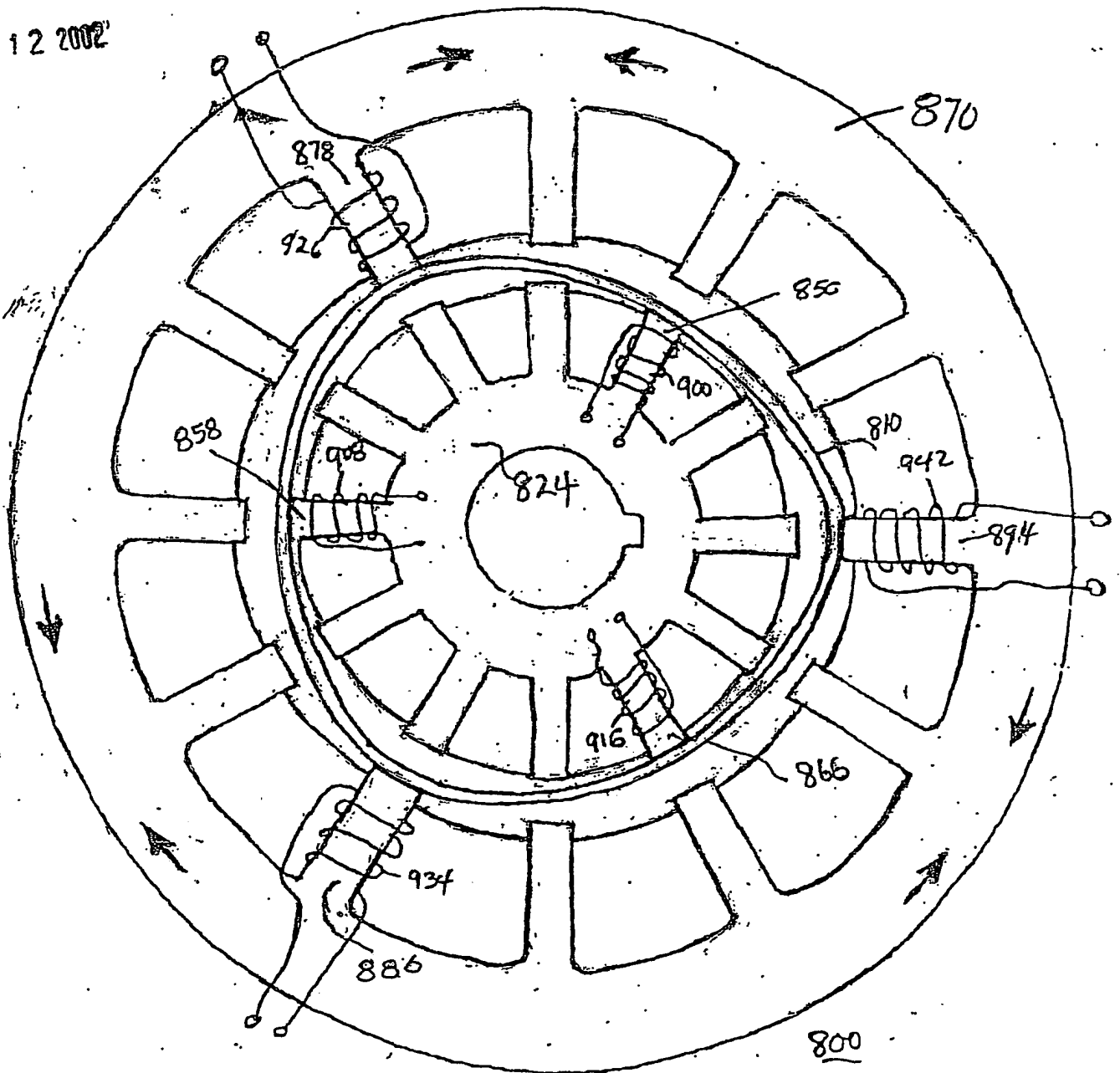


FIGURE 25

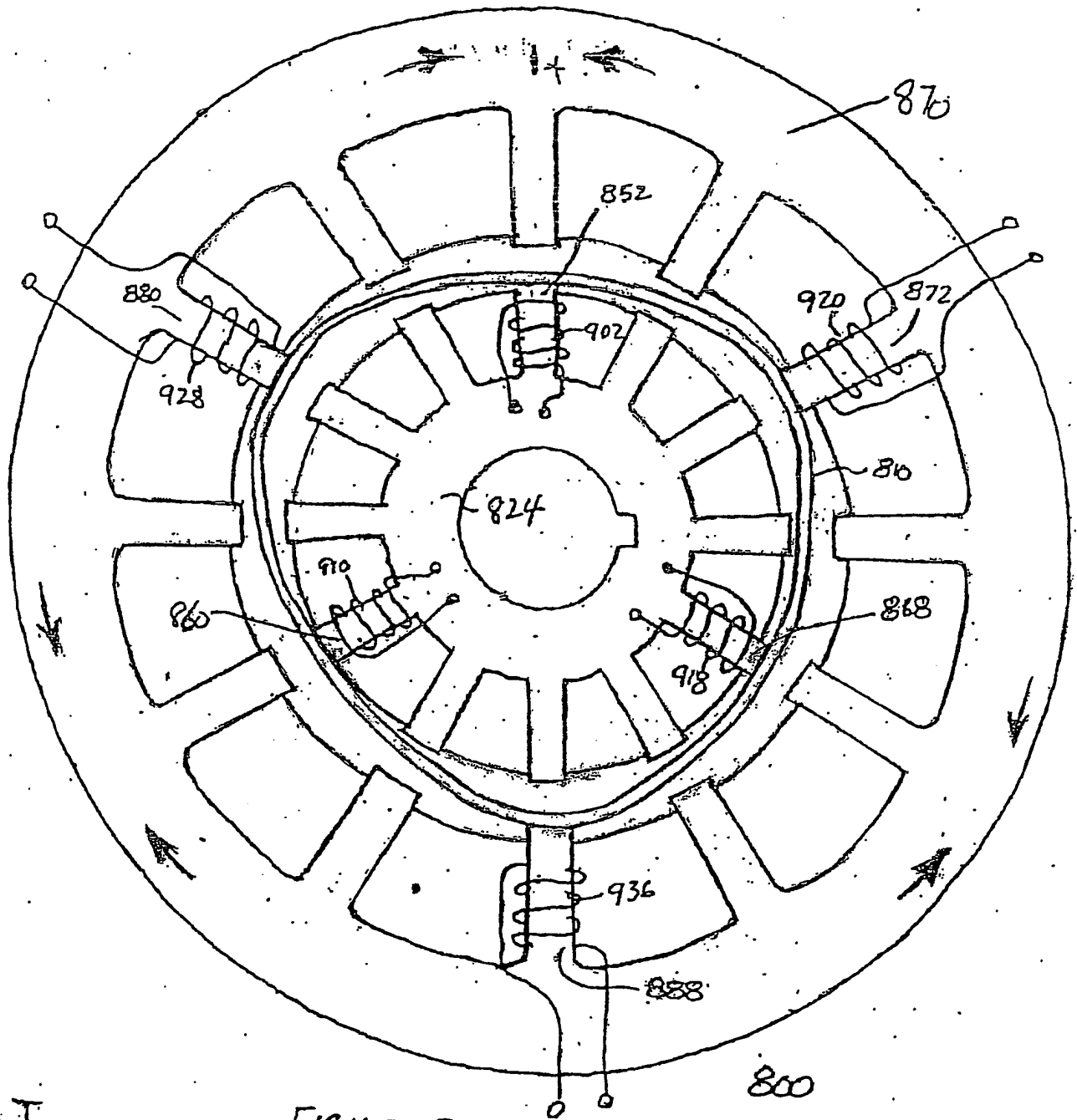


FIGURE 26

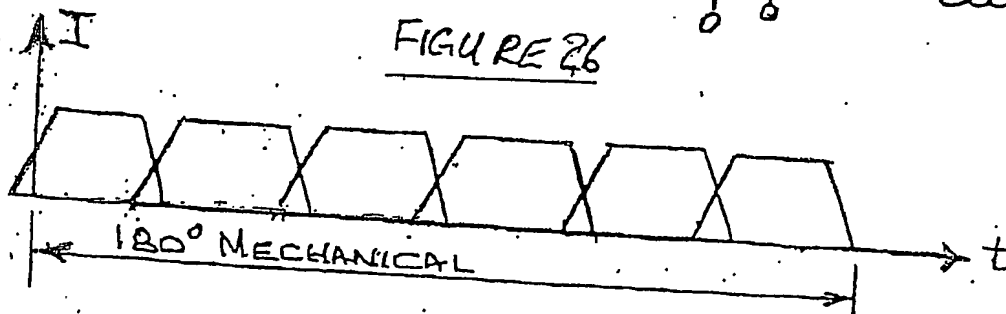


FIG 27

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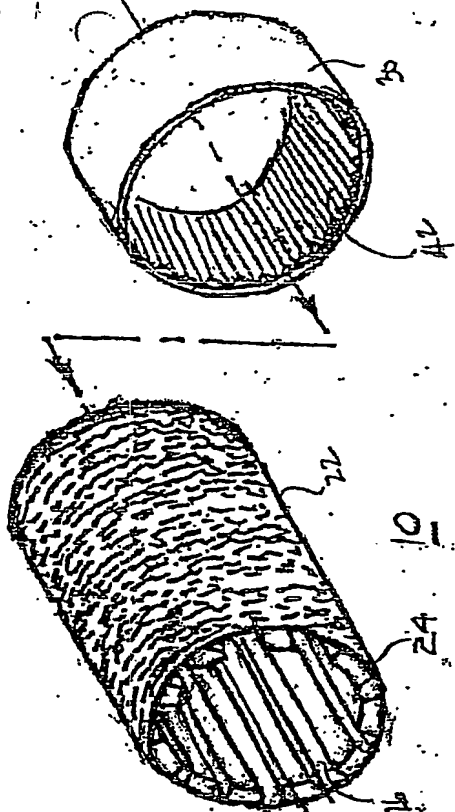


FIGURE 28

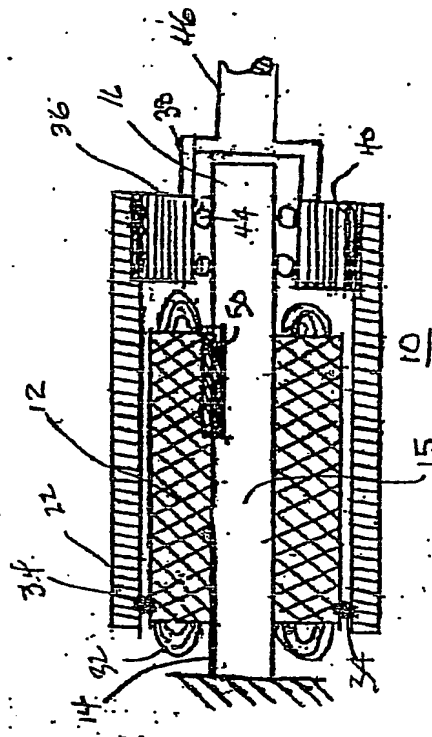
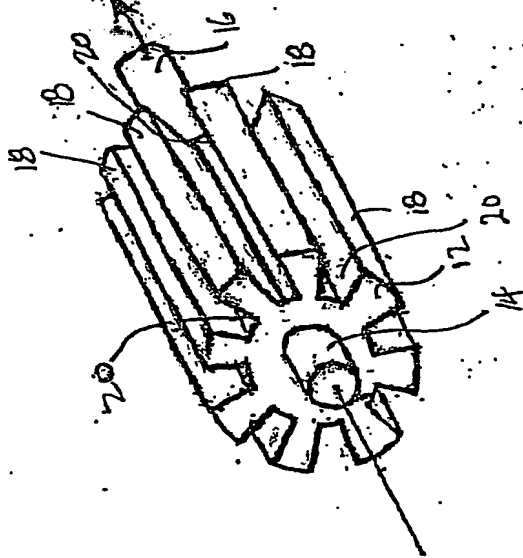


FIGURE 29

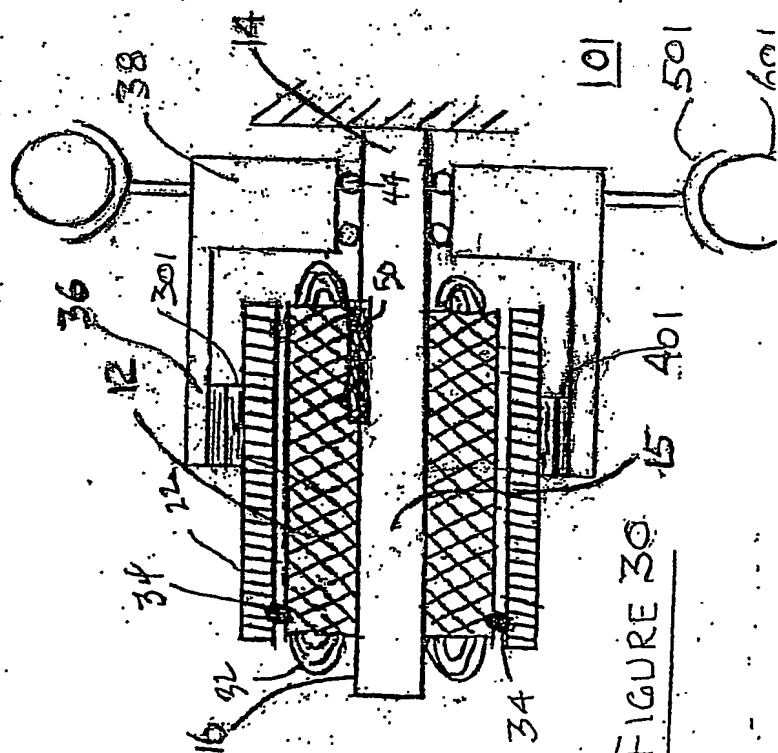


FIGURE 30

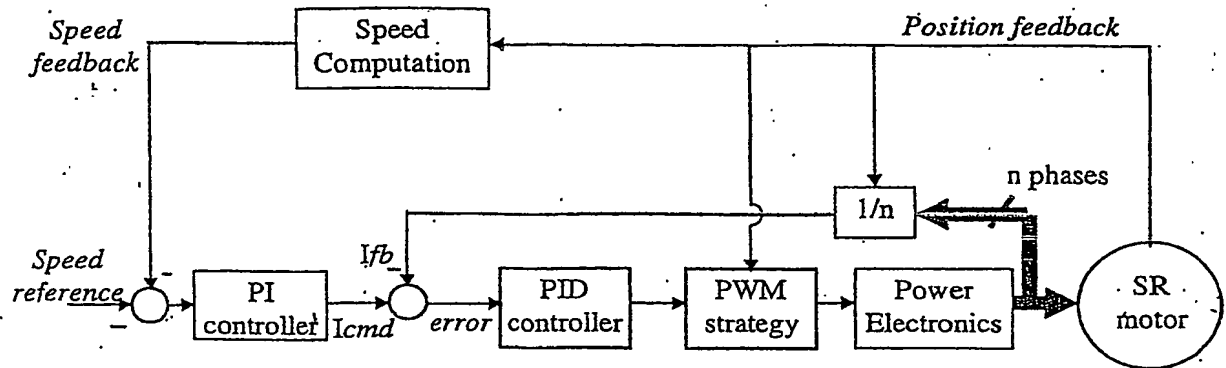


Figure A, Speed and Current Control Loop for an SR Motor

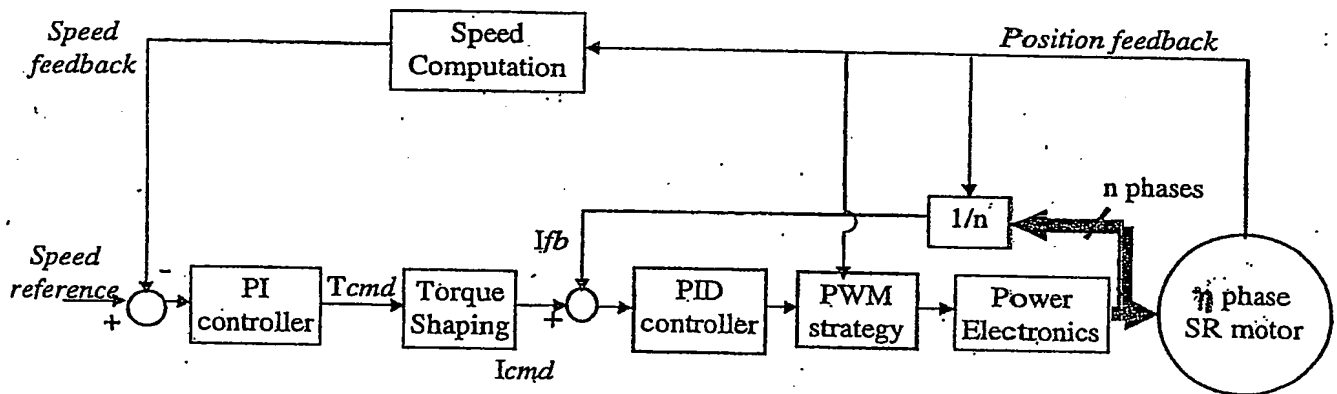


Figure B, Speed and Torque Control Loop for an SR Motor

Below is a complete drive system including the load that may be non-linear.

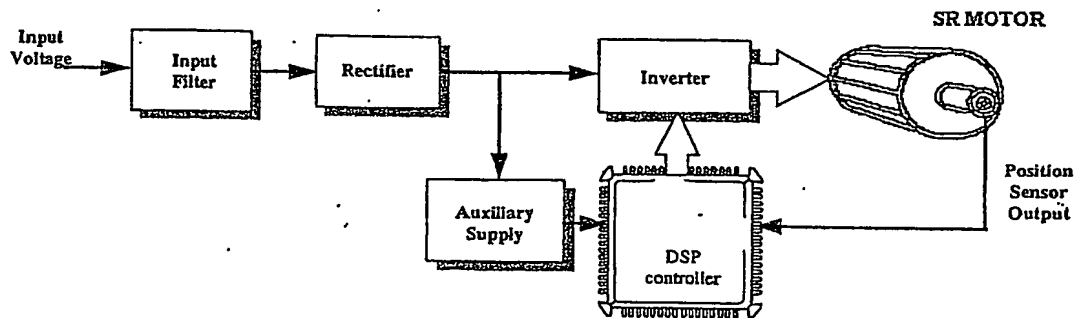


Figure C, Phase Switched Reluctance Motor Driver
(Power Electronics)

Fig 31 A, B, C.

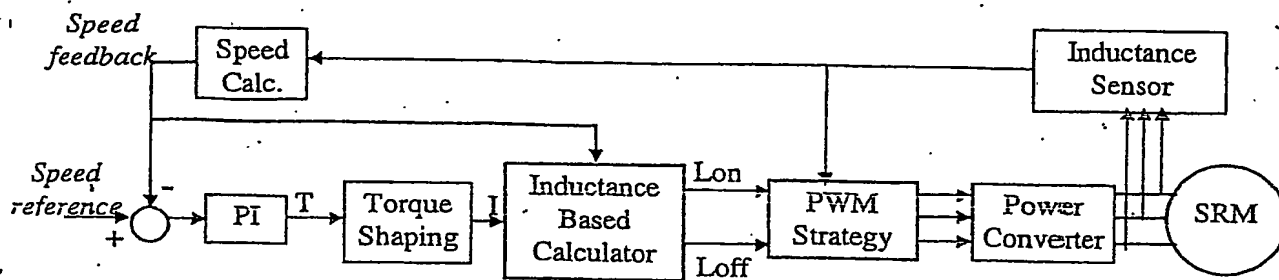


Figure 3.10: Use of Inductance for Direct Commutation

Since there is at least one idle phase in a SRM the inductance of that phase can be sensed for the purpose of commutation control. The phase inductance of the idle phase is estimated from the measurements of the motor terminal voltages and currents. The commutation instants of the active coil are expressed in terms of the phase inductance value of the idle phase: L_{on} and L_{off} . The commutator compares the instantaneous supplied coil inductance L with the values L_{on} and L_{off} and commutates the corresponding coil current.

FIG 31 D

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